

Active particles in external potentials

①

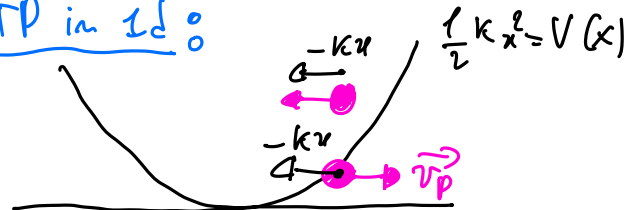
b) Confinement

Harmonic trap $V(x) = \frac{1}{2} k x^2$

$$v_R = v_p - kx \quad \alpha_R = \alpha_L = \alpha$$

$$v_L = v_p + kx \quad P(x, t) = \text{prob to go right/left at } x$$

RTP in 1d:



$$\partial_t P(x, +) = -\partial_x [(v_p - kx) P(x, +)] - \frac{\alpha}{2} P(x, +) + \frac{\alpha}{2} P(x, -)$$

$$\partial_t P(x, -) = -\partial_x [-(v_p + kx) P(x, -)] + \frac{\alpha}{2} P(x, +) - \frac{\alpha}{2} P(x, -)$$

Steady-state: $\partial_t P(x, \pm) = 0 \Rightarrow$ compute $P(x) = P(x, +) + P(x, -)$

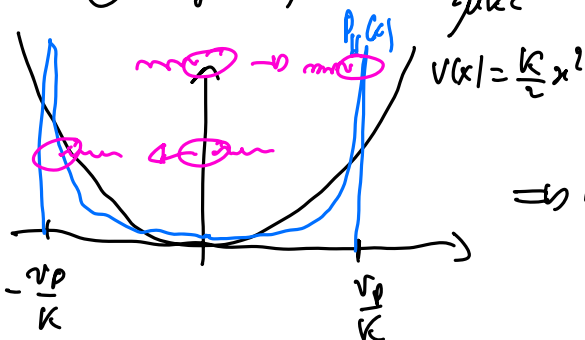
Exact solution: $P(x) = P(0) \left[1 - \left(\frac{kx}{v_p} \right)^2 \right]^{\frac{1}{2} \frac{1}{k\tau} - 1}$ [Tailleur, Carles, PRL 2008]

① if $x > \frac{v_p}{k}$ $v_R < 0$ } bounded horizon $[-\frac{v_p}{k}, \frac{v_p}{k}]$ accessible to the
 $x < -\frac{v_p}{k}$ $v_L > 0$ } particles

② $\tau \rightarrow 0, P=0$ if $x \neq 0 \Rightarrow P(x) \sim e^{\frac{1}{2\mu k\tau} \ln [1 - (\frac{\mu kx}{v_p})^2]}$
 $\sim e^{-\frac{1}{2\mu k\tau} \cdot (\frac{\mu kx}{v_p})^2} = e^{-\frac{\mu kx^2}{2\tau v_p^2}} = e^{-\beta_{eff} \frac{kx^2}{2}}$

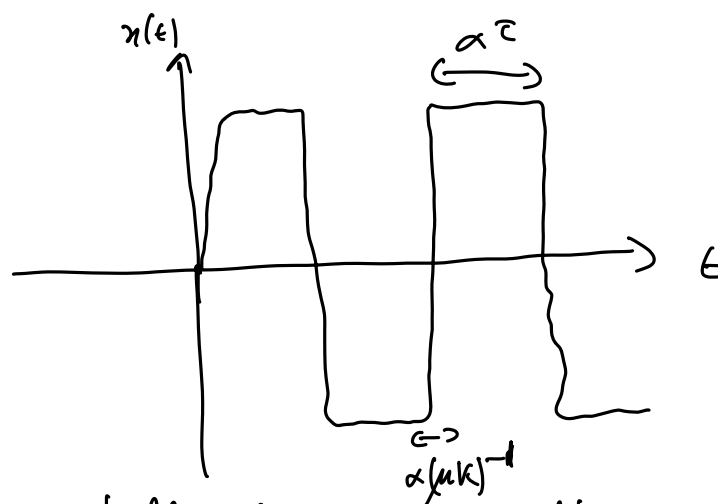
Effective equilibrium with $\ln \tau_{eff} = \frac{v_p^2 \tau}{\mu} = \frac{D_H}{\mu}$

③ large τ , $\tau > \frac{1}{2\mu k\tau} \Rightarrow \frac{1}{2\mu k\tau} - 1 < 0$ $P(x)$ diverges as $x \rightarrow \pm \frac{v_p}{\mu k}$



\Rightarrow Accumulation at the horizon

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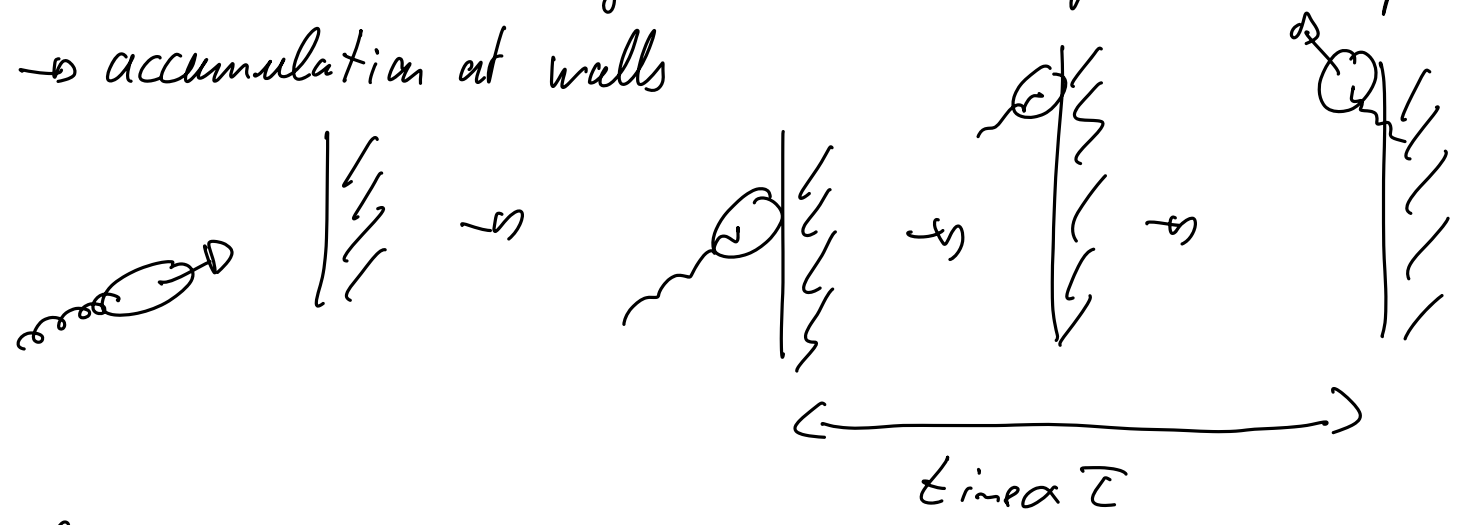
\Rightarrow accumulation at $x = \pm \frac{\sqrt{p}}{K}$

Very different with an equilibrium system \Rightarrow the particles is almost never found at the center of the trap.

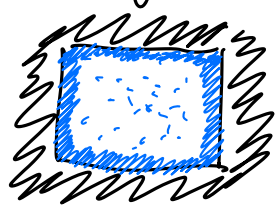
c) active particles and walls

This result is much more general than the case of harmonic traps.

\Rightarrow accumulation at walls



The persistence of active particles make them accumulate at walls



$v_p \tau \gg L \Rightarrow$ all particles at the wall

$P(x)$ is then very different from $e^{-\beta V(x)}$

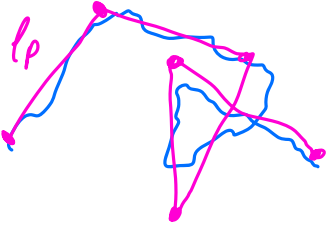
[Elgeti, Gumpner, EPL 2009, 2013]

d) the effective equilibrium regime

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Active particles are characterized by a persistence length ℓ_p and a persistence time τ .

Naive picture: Make steps in a random direction every ℓ_p/τ time units.
 \Rightarrow passive random walk picture!



Exercise: write down the master equation of the particle position \Rightarrow compute the diffusivity.

$$[D] = L^2 \cdot T^{-1} \Rightarrow D \sim \frac{\ell_p^2}{\tau} \times \frac{1}{d}$$

e.g. ABP, $\tau = \frac{1}{D_n}$, $\ell_p = \frac{v}{D_n} \Rightarrow D = \frac{v^2}{d D_n}$ ✓

RTP, $\tau = \frac{1}{\alpha}$, $\ell_p = \frac{v}{\alpha} \Rightarrow D = \frac{v^2}{d \alpha}$ ✓

diffusivity: $\lim_{t \rightarrow \infty} \frac{1}{t} \langle x^2(t) \rangle \sim 2dD$

$\langle x^2 \rangle \sim 2dDt$

⚠ This works because there are no other sources of fluctuations. If v_0 fluctuates, the relation between ℓ_p , τ & D is not universal.

The equilibrium limit

In the limit $\tau \rightarrow \infty$, D constant, active dynamics become fully equivalent to colloidal dynamics at an effective temperature $kT_{\text{eff}} = \frac{D}{\mu}$ where D is the large-scale diffusivity of the active particle and μ is their mobility.

* This explains the $\tau \rightarrow \infty$ result for the dynamic well above.

Take home message

(4)

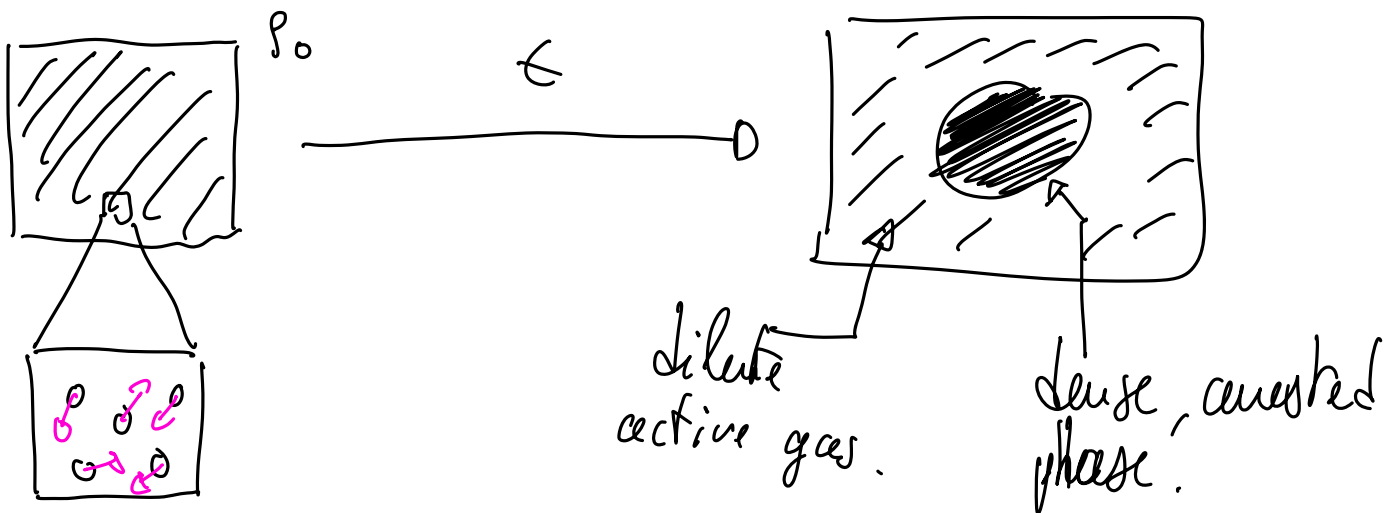
① Universal equilibrium regime at $\tau=0$, D constant
effective temperature: $kT_{\text{eff}} = \frac{D}{\mu}$
where D is the large scale diffusivity of the particle.

② Large $\tau \Rightarrow$ strong non-equilibrium effects

- accumulation at walls
- gravitational collapse
- non-monotonous $P(x)$ in traps.

7.7 Motility-induced phase separation

Phase transition through which an active system undergoes a phase separation resembling liquid-gas phase separation in the absence of attractive forces.



Very general in active matter:

(5)

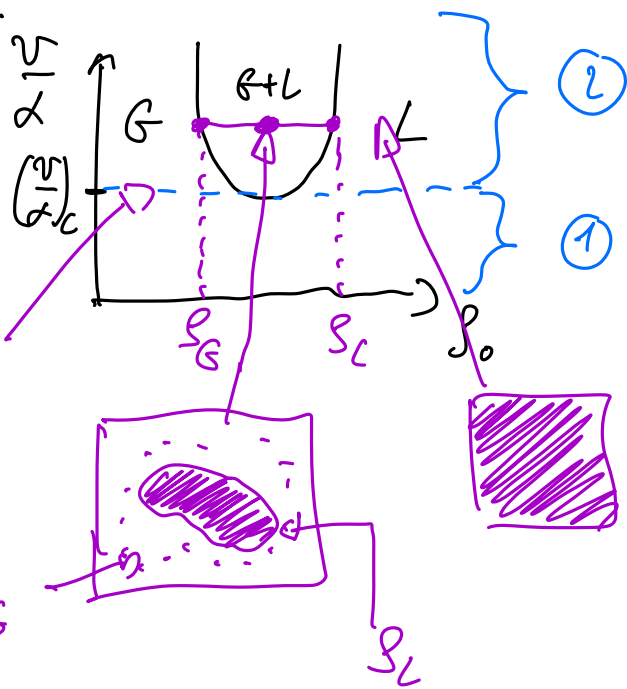
* RTPs [Tailleur, Cats, PRL 101, 218013, (2008)]

on lattice [Thompson et al., J. Stat. Mech. P02029, (2011)]

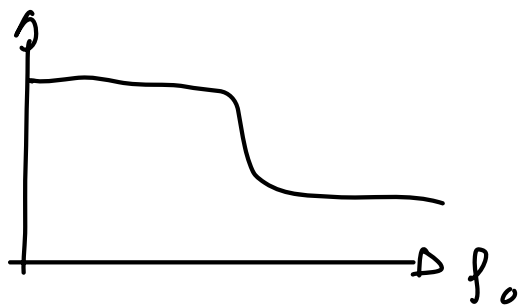
\Rightarrow quorum-sensing information.

$$\dot{\vec{r}}_i = v(\vec{n}_i, [S]) \vec{n}_i(\theta_i)$$

$$\theta_i \xrightarrow{\alpha} \theta_i' + \sqrt{2D_\theta} \vec{z}_i$$



$$v(\vec{n}, p_0)$$



In region (1), the translational noise is strong enough to enforce a homogeneous system.

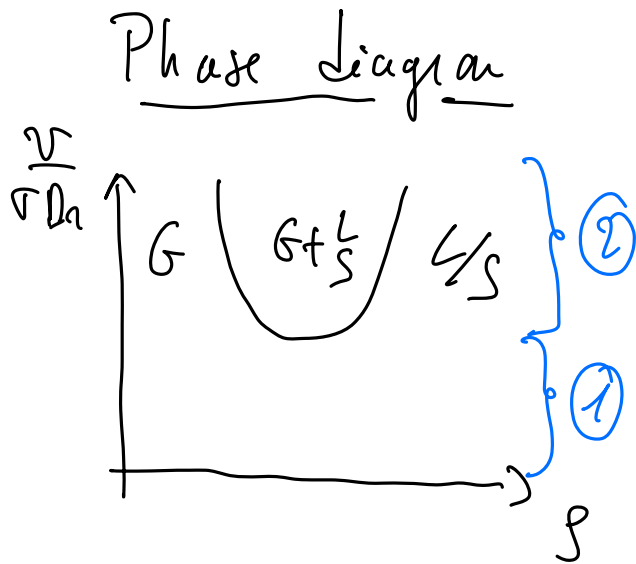
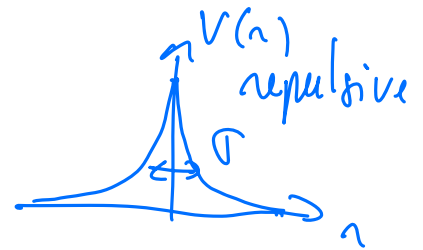
In region (2), Phase-separation is observed.

If $D_\theta \rightarrow 0$, $(v/\alpha)_c \rightarrow 0$; nIPS is seen everywhere.

* ABPs: [Fily, Marchetti, PRL 108, 235702 (2012)] ⑥
 [Redner, Heger, Beshara, PRL 110, 088701 (2013)]

→ pairwise forces

$$\begin{cases} \vec{\pi}_i = v_0 \vec{u}(\theta_i) - \sum_{j \neq i} \vec{\nabla}_{\vec{r}_i} V(\vec{r}_i - \vec{r}_j) \\ \theta_i = \sqrt{2\eta_n} \xi_i \end{cases}$$



In region ①, as in equilibrium, pairwise repulsive forces leads to a homogeneous fluid.

In region ②, phase-separation occurs.

* In experiments:

- Enhanced tendency for clustering: [Thurnhauser et al, PRL 108, 268303 (2012); Palacci et al., Science 339, 936 (2013)]
- Phase separation: [Buttinoni et al., PRL 2013, 110, 238301]
- self-propelled Janus colloids

→ Bacterial colonies: [Lin et al, PRL 122, 248101, (2019)]

→ Quinche rollers: [Geyu et al, PRX 9, 031043 (2019)] (7)
 Coexistence between ordered polar active liquid
 & an arrested solid.

7.7.1) A linear stability analysis

ABPs or RTPs interacting via quorum-sensing interaction
 $v(g(n))$

① Non-uniform speed $v(\vec{n})$ without interactions in 2D with PBC

$$\partial_t P(\vec{n}, \theta) = - \vec{\nabla}_{\vec{n}} \cdot [v(n) \vec{u}(\theta) P(\vec{n}, \theta, t)] + \text{isotropic reorientation terms } \textcircled{H} \cdot P$$

$$\text{ABPs: } \textcircled{H} P = D_n \partial_{nn} P(\vec{n}, \theta)$$

$$\text{RTPs: } \textcircled{H} P = -\alpha P(\vec{n}, \theta) + \alpha \int \frac{d\theta}{2\pi} P(\vec{n}, \theta')$$

$$\text{Steady-state } \partial_t P(\vec{n}, \theta) = 0$$

$$\textcircled{\alpha} P(\vec{n}, \theta) = f(\vec{n}) \text{ then } \textcircled{H} P = 0$$

$$\textcircled{\beta} \vec{\nabla}_{\vec{n}} \cdot [v(\vec{n}) \vec{u}(\theta) f(\vec{n})] = 0 \Rightarrow f(\vec{n}) = \frac{\kappa}{v(\vec{n})}$$

$$\vec{\nabla}_{\vec{n}} \cdot [\underbrace{\kappa \vec{u}(\theta)}_{\text{no } \vec{n}\text{-dependency}}] = 0$$

$$\Rightarrow \text{Steady-state } \boxed{P_{ss}(\vec{n}, \theta) = \frac{\kappa}{v(\vec{n})}}$$

Active particles spend more time when they go slowly
 \Rightarrow accumulation in slow regions

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① Repulsive force / crowding: model $v(g(n))$ with $v'(g) < 0$
 \Rightarrow particles that go slower where are denser.

① model a lack of food \rightarrow quorum-sensing [Cenatolo et al, Nat. Phys. 2020]
 ② pairwise forces

$$\vec{\dot{n}}_i = v_0 \vec{u}(\theta_i) + \vec{F}_i; \quad \vec{F}_i = - \sum_j \vec{\nabla}_{\vec{n}_i} V(\vec{n}_i - \vec{n}_j)$$

$$= \underbrace{[v_0 + \vec{F}_i \cdot \vec{u}(\theta_i)] \vec{u}(\theta_i)}_{= "v(g)" \vec{u}(\theta_i)} + (1 - \vec{u}(\theta_i) \vec{u}(\theta_i)) \vec{F}_i$$

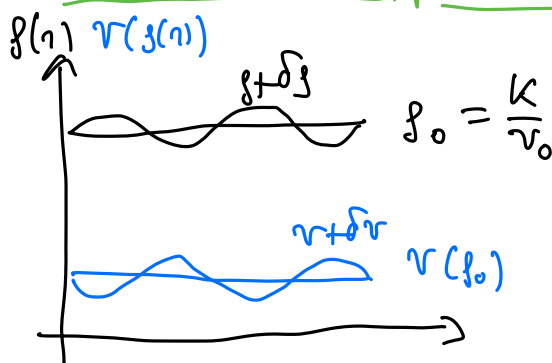
MF + neglect 2nd term.

Repulsive forces lead to a decrease of $v(g)$ as

$$v(g) \approx v_0 \left(1 - \frac{g}{g^*}\right) \quad [\text{Fily et al, PRL 2012}]$$

\nwarrow crowding density

Feed back loop leading to MIPS:



$$\text{Perturbation } g(n) = g_0 + \delta g(n)$$

$$\delta g(n) \ll g_0$$

$$\begin{aligned} \text{Since } v(g(n)) &= v(g_0) + \delta v(n) \\ &= v(g_0) + v'(g_0) \delta g \end{aligned}$$

Q: where does $g(\vec{n})$ wants to relax?

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$g(\vec{n})$ is a conserved field \Rightarrow its evolution on large scales is slow

Locally particles want to relax towards $g(\vec{n}) \propto \frac{\kappa}{v(\vec{n})}$

$$\frac{\kappa}{v(g(n))} = \frac{\kappa}{v(g_0) + v'(g_0) \delta g} = \frac{\kappa}{v(g_0)} \cdot \frac{1}{1 + \frac{v'}{v} \delta g} = \underbrace{\frac{\kappa}{v(g_0)}}_{g_0} \left(1 - \frac{v'(g_0)}{v(g_0)} \delta g \right)$$

Start from $g_0 + \delta g$; relax to $g_0 - \frac{v'(g_0)}{v(g_0)} g_0 \delta g$

(if) $|\delta g| < \left| -\frac{v'}{v} g_0 \delta g \right| \Rightarrow$ perturbation is amplified \Rightarrow instability

linear instability criteria:

$$\boxed{\frac{v'(g_0)}{v(g_0)} < -\frac{1}{g_0}}$$

Conclusion: When $v'(g_0)$ is sufficiently negative, this hand-waving argument predicts a linear instability.

Q: Can we derive this quantitatively in a specific model?

Comment: This argument can be made more quantitative and can be generalized to non-vanishing translational diffusion
[Cates, Tailleur, Ann. Rev. Cond. Mat. Physics 6,
219-244 (2015)]